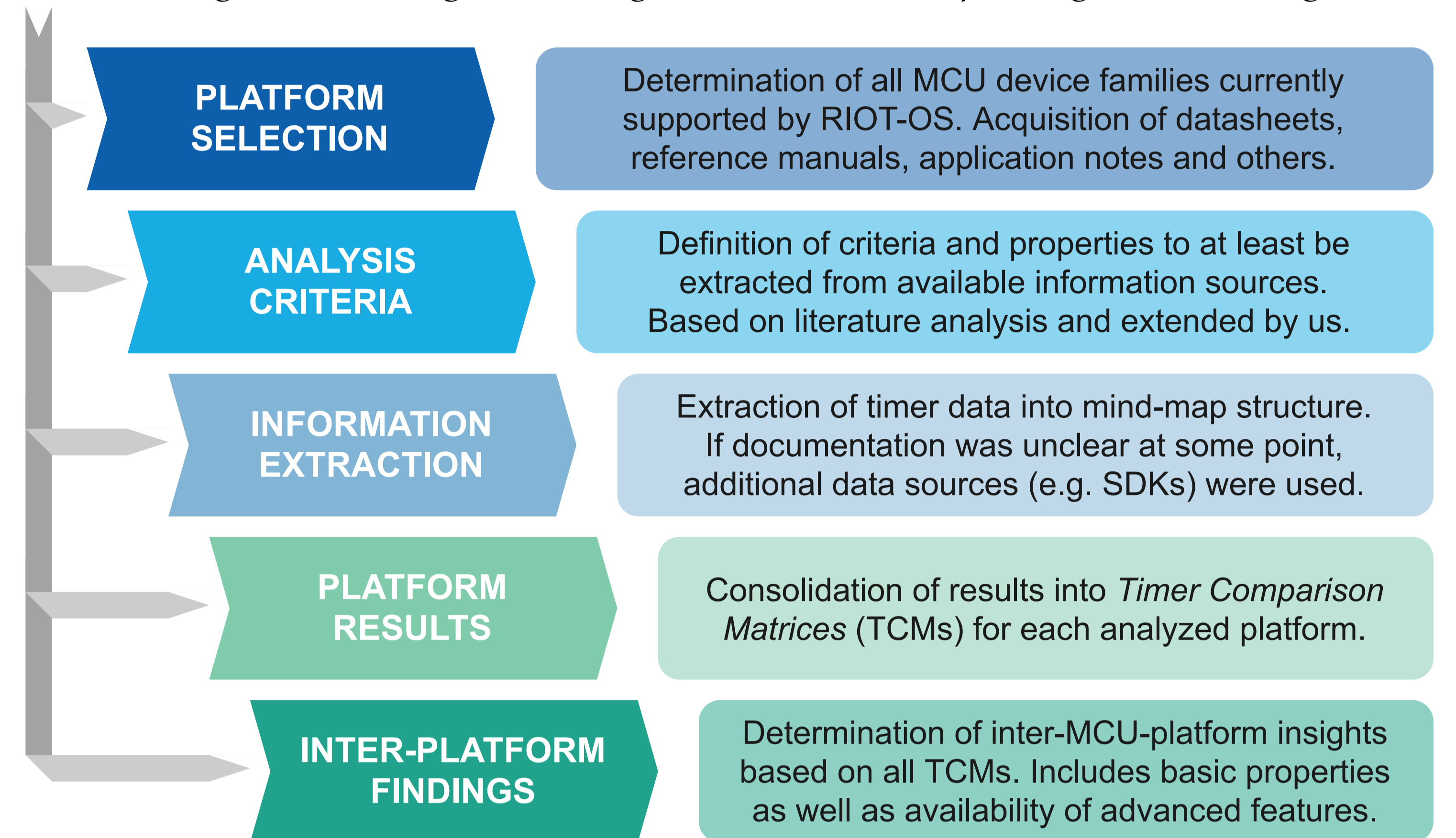


Scan to **download paper** and get additional information.



- TIMER-HARDWARE ANALYSIS — 2

Gaining detailed insight into target hardware, underpinning the API design.



- RIOT-OS TIMER MODULE REVIEW — 3

Review of existing low-level timer implementations and their limitations.

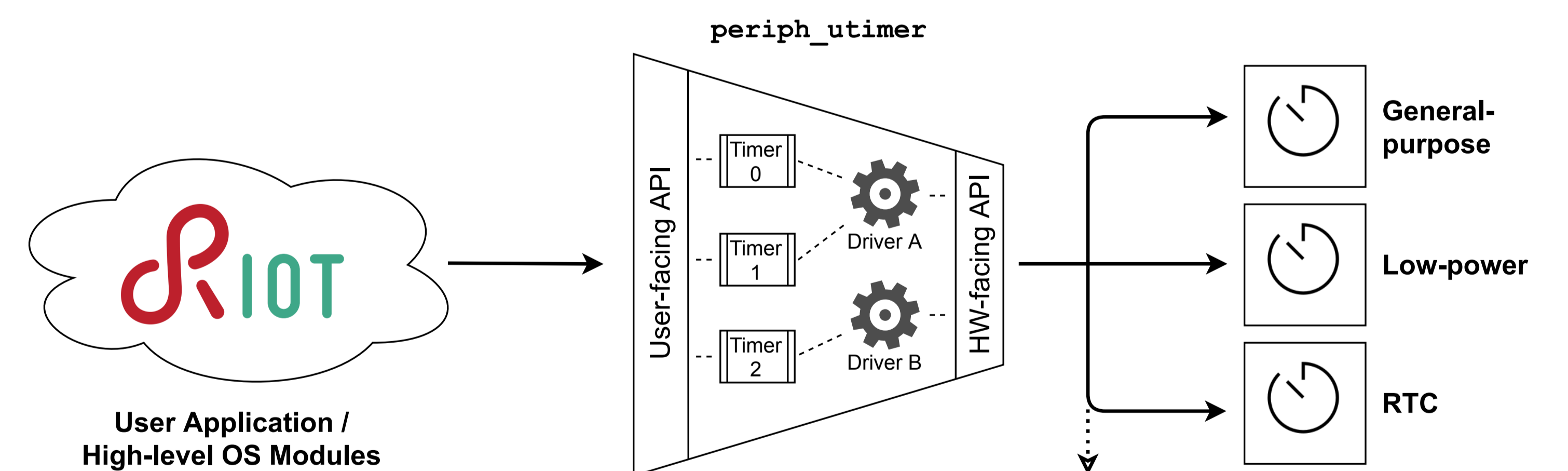
- Reduced to minimal common function set
- Functionality often overlaps between modules
- Neither exposing all hardware timers nor all their basic features (e.g. compare channels)
- Peripheral allocation conflicts between modules
- Application developers are often required to write driver code for features (e.g. low-power modes)
- Timer selection and configuration highly heterogeneous and requires changes to OS header files

RIOT-OS Modules

- periph/
 - timer (🕒)
 - rtc (🕒)
 - rtt (🕒)
 - pwm (📊)
 - wdt (🐾)

- LOW-LEVEL TIMER API DESIGN — 5

Streamlining existing APIs into a uniform interface, fostering flexible use of available timers and features while preserving application portability whenever possible.



User-facing API uAPI
Single set of timer type abstracted functions, exposed to the user application and high-level system modules

Hardware-facing API hAPI
Compact and reusable timer drivers for each used timer type, directly interfacing the various hardware peripherals.

- Timers interactively configured via KConfig
- Static properties and run-time status information provided to application and OS modules
- Similar functions are bundled within the hAPI
- Separate handling of CMP and OVF interrupts
- Run-time (re-)configuration of clock sources
- Virtual drivers allow representation of chained timers as atomic instances, extending existing driver code

