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uTimer: A Uniform Low-level Timer API for RIOT OS

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Introduction

- Timers are fundamental parts of every embedded system
- MCU manufacturers offer a wide range of peripherals, including:
 - General-purpose timers
 - Low-power timers
 - High-speed timers
 - Real-time clocks (RTCs)
- Each timer type possesses its own feature-set

The Challenge

Embedded OSs need to keep up with the ever-growing variety of timers.
Offering broad out-of-the-box peripheral support while maintaining application portability is challenging.

The Problem of Abstracting Timer Hardware

The Abstraction Trade-off

 vs. 

Direct HW-register access

Yields **Near-optimal performance**, but is **highly error-prone, laborious, and prevents portability**.

Strongly abstracted timer API

Is **portable and user-friendly**, but **decreased performance**.

The Time-memory Trade-off

 vs. 

Mitigation of performance loss is partly possible by sacrificing system memory to reduce computational complexity

Choosing an appropriate level of abstraction therefore is challenging.



The friendly Operating System for the
Internet of Things

 RIOT-OS  <https://riot-os.org>

Free open-source embedded OS for resource constrained IoT devices.
Aims to implement all relevant open standards supporting an Internet of
Things that is connected, secure, durable & privacy-friendly.





Current Low-level Timer APIs in RIOT OS

Three generic modules interface common timer types and two special-purpose modules provide higher-level features, such as signal generation.

- Only basic timer operations supported
- Module functionality overlaps, but APIs differ in use and exposed features
- Underlying timer types differ between MCUs
- Peripherals can simultaneously be used by multiple APIs (resource allocation conflicts)
- Timer selection and configuration via platform-dependent headers files

Modules

periph/

- timer ()
- rtc ()
- rtt ()
- pwm ()
- wdt ()

Application developers should not
(re-)write low-level driver code!



A Unified Timer API for RIOT OS

Our Goal

Streamline existing APIs into a uniform interface, fostering a transparent and interchangeable use of all available timer peripherals. Provide basic timer functions and out-of-the-box support for device-specific feature, while preserving platform-independence whenever possible.

To base our API design on, we conducted . . .

- Large-scale analysis of timer hardware
 - Covering 43 device families from 8 different manufacturers
- Review of existing low-level timer modules
- Survey of related work

Key Design Aspects

- Separation of hardware-facing (hAPI) and user-facing API (uAPI)
- One low-level driver `utim_driver_t` per timer type
- Exposed timers represented by a `utim_periph_t` instance, referencing corresponding `utim_driver_t` and providing static timer properties
- Interactive timer selection and configuration via Kconfig

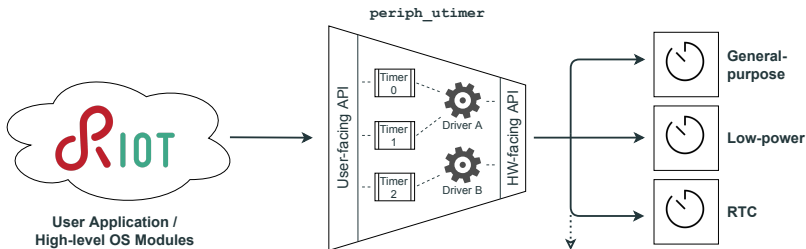


Figure 1: Architecture of the proposed low-level timer API design



One low-level driver struct `utim_driver_t` per timer type

- Consisting of minimal function pointer sets
- Common basic features are directly accessible and device-specific features are exposed via a compact property interface
- Related functions are bundled into single calls
- Driver granular reusability across timer types
- Function granular reusability across drivers
- Virtual drivers allow representation of chained timers as one atomic timer instance, re-using existing driver code

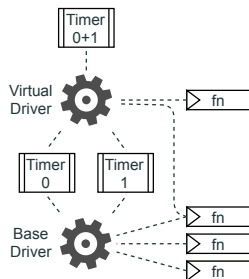


Figure 2: Virtual timer driver

A single set of functions, independent of the underlying timer type

- Function calls are either directly delegated to the driver or implemented as multiple subsequent hAPI driver calls
- Previously bundled hAPI functions are unbundled
- Static attributes and run-time dynamic properties are made available
- Compare match and overflow interrupts can be handled separately
- Clock source is run-time configurable

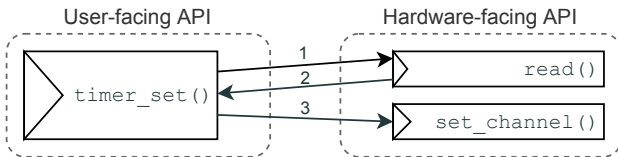


Figure 3: Compound uAPI function consisting of multiple hAPI driver calls

Validation and Evaluation

Validation and Evaluation

1. **Cross-platform Validation** via automated platform-independent test suites with CI integration.
2. **Performance Benchmarks** using a HiL testbed with CI integration, comparing the existing `periph_timer` to our novel `periph_utimer`.

🔧 Scope

- STMicroelectronics: STM32L476RG (Nucleo-L476RG)
- STMicroelectronics: STM32F070RB (Nucleo-F070RB)
- Silicon Labs: EFM32PG12B500 (SLSTK3402A)
- Espressif Systems: ESP32 (ESP32-WROOM-32)

Selected MCUs cover different manufacturers, CPU architectures, counter widths from 16 to 64 bit, common basic timers, advanced ultra low-power peripherals and chainable timers.

Performance Benchmarks – HiL Testbed



Figure 4: One rack of the RIOT HiL testbed used for our benchmarks.

Performance Benchmarks – Overview

The following aspects were assessed by our benchmarks:

1. PHiLIP hardware limits
2. GPIO Latency
3. API abstraction overhead
 - User-facing API
 - Hardware-facing API
 - No additional abstraction
4. Timer base operations
 - Read counter register
 - Write counter register
 - Set channel
 - Clear channel
5. Timeout latency

Isolating the APIs abstraction overhead:

- Read and write operations replaced with no operations (NOPs)
- Operations performed via both uAPI and direct hAPI driver calls
- Measured execution time converted to equivalent CPU cycles

API Abstraction Overhead

- Abstraction via uAPI introduces 6 CPU cycles
- No generic hAPI overhead
 - One additional CPU cycle on STM32 due to pipeline refill artifacts.

Performance Benchmarks – Timeout Latency

Timeout latency, jitter and error were assessed:

- Timer frequencies between 10 kHz and 10 MHz
- Timeout durations between 10 μ s and 1 s
- Duration between arming and callback execution is measured
- Difference of expected and actual timeout length is calculated

Timeout Latency and Error

1 ms @ 1 MHz

Timeout latency L_{tout} increased by between 0.77 μ s on the SLSTK3402A (best) and 2.32 μ s on the ESP32 (worst).

The respective timeout error E_{tout} therefore only increased by between 0.08 % (best) and 0.23 % (worst).

⚠ Edge case: Very short timeouts ($\leq 10 \mu\text{s}$)

- Every slight increase in timeout latency L_{tout} significantly contributes to the timeout error E_{tout}
 - In such cases, unnecessary indirection should be avoided
 - Direct hAPI use or active waiting (i.e. spinning) is recommended
-

✓ Edge case: Long-running timeouts ($\geq 1 \text{ s}$)

- Impact of timeout latency L_{tout} increase on timeout error E_{tout} becomes insignificantly small
- Other factors, such as oscillator accuracy, become dominant

The proposed uTimer API streamlines existing RIOT-OS modules into a uniform interface.



- Abstraction and time-memory trade-offs were successfully balanced, allowing convenient use while maintaining performance.
- Both platform-independent and platform-specific timer features are exposed, preserving portability whenever possible.
- Application developers are relieved from modifying OS code and deep diving into vendor datasheets or SDKs.

Questions ?

Discussion !

Appendix

STM32L476RG Timer Support in RIOT OS

RIOT-OS Modules

periph/

- timer (📦)
- rtc (🕒)
- rtt (🕒)
- pwm (📊)
- wdt (🐾)

STM32L476RG Peripherals

- General-purpose timer (1/7 📦) (2/7 📊)
 - 32- and 16-bit
- Basic timer (0/2)
- Advanced-control timer (1/2 📊)
- Low-power timer (1/2 🕒)
- Real-time-clock (1/1 🕒)
- SysTick timer (0/1)
- Watchdog (1/2 🐾)

🕒 Peripheral Availability

- Only 35% of the available timers are actually usable
- 2 timer types are not exposed by any periph module

Performance Benchmarks – Setup Architecture

Benchmarks consist of a RIOT-based test firmware and a Robot Framework (RF) test suite.

GPIO traces are captured during benchmarks. Measurement start and stop is signaled by consecutive rising and falling edges. Hardware limits like GPIO latency and hold-off times are accounted for.

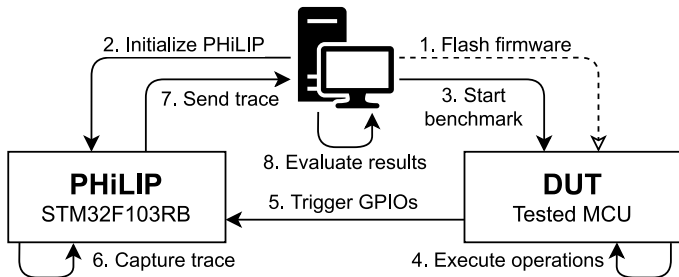


Figure 5: Architecture of our benchmarking setup

Additional Evaluation Findings

During our evaluation we further found:

- **ROM size** on 32-bit devices increased by 12 bytes per configured timer peripheral and 28 bytes for every required timer type driver.
- **RAM use** was not affected by uTimer.
- Number of out-of-the-box **available peripherals and channels** significantly increased and advanced timer types are supported.
- **Code quality and usability** benefited from the streamlined API.